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## **Probabilistic Robotics - Universiteit Van Amsterdam**

"Computational Principles Of Mobile Robots" [1].  
References [1] G. Dudek And M. Jenkin, Computational Principles Of Mobile Robotics, Cambridge University Press, 2nd Edition, 2010. [2] S. Thrun, W. Burgard And D. Fox, Probabilistic Robotics (Intelligent Robotics And Autonomous Agents), The MIT Press, September 2005, ISBN 0-262-20162-3. 4 Mar 10th, 2024

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Probabilistic Neural Network (generally Divided Into Four Layers: Input Layer, Model Layer, Summation Layer And Output Layer. Input Layer As The Training Sample,  $X=(x_1,x_2,\dots,x_q)^T$  To Remember, The Neuron Number And Sample Vector Dimension Equal. In The MATLAB Programming A Probabilistic Neural Network To Create The Code For Net = Newpnn(P,T ... Mar 6th, 2024

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