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Errors. Following The Invention Of The Origin-Based Assignment (OBA) Algorithm By Bar-Gera (2002), Such Precision Is Now Possible; See Patriksson (1994) For An Overview Of These Models And Solution Methods. The Findings Of The Comparison Of User-optimal And System-optimal Route Patterns Presented Below May Be Surprising As Well As Informative. 1th, 2024

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$663 \theta'' = U \cos \theta - (M + m)g \sin \theta + ml(\cos \theta \sin \theta) \theta'^2 - Ml \cos^2 \theta - (M + m)l$ . (7) Fig.2 Vector Diagram For Force Components In Torque Balance Equations(6) And(7)represent 1th, 2024

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(2.1-9a) (2.1-9b) TABLE 2.1-1 Discrete Nonlinear  
Optimal Controller System Model:  $= F_k(X_k, 11k), K > 1$   
Performance Index:  $K=i$  Hamiltonian: Optimal  
Controller State Equation:  $= F_k(X_k, 11k)$  — Costate  
Equation:  $\delta X_k \delta L_k A_{Xk}$  1th, 2024

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Definition 5 (Lie Algebra Of  $F$ ) Let  $F$  Be A Family Of Smooth Vector fields On A Smooth Manifold  $M$  Denote By  $\tilde{L}(M)$  the Set Of All  $C^1$  Vector fields On  $M$ . The Lie Algebra  $Lie(F)$  Generated By  $F$  Is The Smallest Lie Subalgebra Of  $\tilde{L}(M)$  Containing  $F$  1th, 2024

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