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The Regulation Is Achieved By A PID Controller. Simulink Model Of The Closed Loop Converter Is Shown In Figure 7b. Simulink PID Control Block Is Illustrated In Figure 7c . The Parameters Used For The Closed-loop Simulation Are : $V_i = 12 \text{ V}$ $L = 300 \text{ H}$ $C = 9 \text{ mF}$ 9th, 2024

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3 Agenda -Day 2 Day 2 10:00 Am -11:00 Pm •Mechanical Engineering And Control System Concepts Using MATLAB And Simulink. Mechanical Enginee 1th, 2024

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