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That's An Expansion By A Factor Of 2. Note That Every Vector Is A 2-eigenvector. In Other Words, All Of R2 Is The 2-eigenspace. Figure 6: Expansion Figure 7: Contraction Figure 8: Half Turn A Scalar Matrix Is A Multiple Of The Identity Matrix Like T 4th, 2024

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18 (a) The System Has A Unique Solu-tion; The Three Planes Have A Unique Point Of Intersection; (b) The System Has Infinitely Many Solutions; The Three Planes Inter-sect In A Line, Or The Three Planes Intersect In A Plane. ... -3x 7th, 2024

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