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Digital PID Controller Design Digital PID Controller Design Digital PID Controller Design ² Let $T = \{t_1, t_2, \dots, t_K\}$ Denote The Real Distinct Zeros Of $T(s; \frac{1}{2})$ of odd Multiplicity, For $U \in \mathbb{R}^2$ ($i=1, 1$), Ordered As Follows: $t_1 < t_2 < \dots < t_K$