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Subsystem And An Under-actuated Subsys-tem [9]. Then, He Controlled Them With A PID Controller And A Sliding Mode Controller, Respectively. As A Result, ... Section 2 So That The Adaptive Robust Control For The Alti-tude Control Of The Helicopter Can Be Designed In Section 3. Then, Section 3 Will Discuss An Adaptive Robust ... Jan 6th, 2024.

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